

<b>Course Title</b>	<b>Automatic Control</b>
<b>Course Code</b>	<b>EE3409</b>
<b>No. of Credit Hrs (Lecture + Tutorial + Lab)</b>	<b>4 (3+0+1)</b>
<b>No. of Contact Hrs (Lecture + Tutorial + Lab)</b>	<b>5 (3+0+2)</b>
<b>Level-Year</b>	<b>6-3</b>
<b>Prerequisite (if any)</b>	<b>EE3302</b>

**1) Course Objectives:**

The main objective of the course is to acquire the basic concepts of control systems' analysis; particularly, to learn the basics of control systems representations/modeling and stability analysis (in time and frequency domains), in addition to practical experiment in the laboratory.

**2) Expected Learning Outcomes:**

Upon completion of this course, student will be able to:

1. Identify and describe the fundamentals of modeling electrical, mechanical, and electromechanical systems. PLO1 [1]
2. Summarize and explain the properties of feedback control systems and basic control actions. PLO1 [1]
3. Apply control system design techniques to single-variable continuous systems in both time and frequency domains. PLO2 [2]
4. Model and investigate electrical, mechanical, and electromechanical systems using practically relevant techniques. PLO3 [6]
5. Communicate and collaborate effectively in teams to propose simple and relevant control system applications. PLO7 [5]
6. Engage in self-directed learning to explore modern control strategies and their applications. PLO9 [7]

**3) Course Contents**

1. System Representation,
2. State Variable Analysis,
3. Stability Analysis,
4. Time Domain Analysis,
5. Root Locus, Bode Plots, Nyquist Plots,
6. System Modelling,
7. Introduction to Basic Control Design.

**4) Automatic Control Lab Contents:**

Experiments are organized in several groups of real time applications, such as:

1. Step Response analysis of 1st and 2nd order System.
2. Frequency Response of 1st and 2nd order System.
3. Root Locus Plot of a given system.
4. Bode plots of a given system
5. Nyquist plots of a given system
6. Lead-Lag compensation design
7. PID controller design
8. Speed control of DC motor
9. Position Control.



**5) Teaching Methods:**

- Lectures and Discussion
- Videos
- Self-learning
- Laboratory demonstrations

**6) Mode of Evaluation: Course Assessment Methods**

- Quizzes , Assignment, Homeworks, Reports, Presentations etc.
- Lab Work
- Mid Exam
- Final Exam

**Evaluation**

No	Assessment Activities *	Percentage
1.	Assignments/Quizzes/HomeWorks/Mini-Projects/Presentations/Reports+Quizzes	15%
2.	Mid Exam	25%
3.	Lab/Tutorial (Lab Exam)	10%
4.	Lab/Tutorial (Lab Reports)	10%
5.	Final Exam	40%

**7) Textbook(s):**

- Control System Engineering, Norman S. Nise, 5<sup>th</sup> Edition, John Wiley & Sons
- Lab Manual.

**8) References:**

- Modern Control Engineering (4th edition) by K. Ogata, 2002
- Feedback Control of Dynamic Systems by Gene F. Franklin, J. David Powell and Abbas Emami Naeini, 4th Edition, Prentice Hall, 2002.